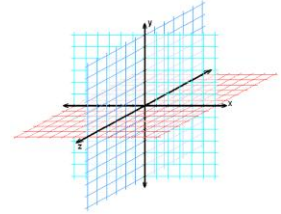


## T5.1 – 3D Vectors

IB Math SL1 - Santowski

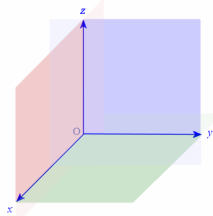
### (A) 3D Grid

- To be able to work in 3 space, we will set up a "grid" so that we can discuss points & vectors
- Here is an illustration of our "grid"
- We have our origin as well as 3 mutually perpendicular axes called the x-axis, y-axis and the z-axis
- We will then also have 3 co-ordinate planes → the xy plane, the xz plane and the yz plane



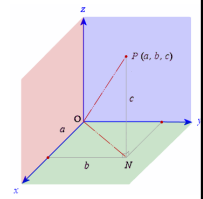
### (A) 3 Space – Co-ordinate Planes

- The **x-y plane** is horizontal in our diagram above and shaded green. It can also be described using the equation  $z = 0$ , since all points on that plane will have 0 for their z-value.
- The **x-z plane** is vertical and shaded pink above. This plane can be described using the equation  $y = 0$ .
- The **y-z plane** is also vertical and shaded blue. The y-z plane can be described using the equation  $x = 0$ .



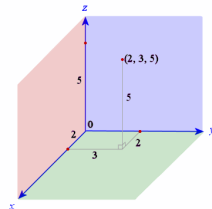
### (B) Points and Vectors in 3 Space

- Any point in 3 space can be described by an ordered triplet  $\rightarrow (x,y,z)$  which correspond to the point's location along the x-, y-, and z-axis (as in 2 space)
- Once we have a point located, say P, we can construct the corresponding position vector,  $OP$
- And since we have a vector now drawn, we can determine its length, and write it in component form



### (B) Points and Vectors in 3 Space

- So consider the point  $A(2,3,5)$ , we can determine its length:
- We can write it in component form as:
- Or we can find its midpoint



### (B) Points and Vectors in 3 Space

- So consider the point  $A(2,3,5)$ , we can determine its length:

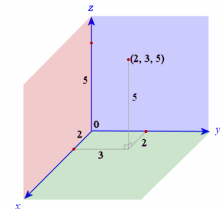
$$|OP| = \sqrt{(2-0)^2 + (0-3)^2 + (0-5)^2} = \sqrt{38}$$

- We can write it in component form as:  $OP = \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix}$

- Or we can find its midpoint

$$MP = \left( \frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}, \frac{z_1 + z_2}{2} \right)$$

$$MP = \left( 1, \frac{3}{2}, \frac{5}{2} \right)$$



### (C) Unit Vectors in 3 Space

- We can introduce our special unit vectors in 3 space as well the unit vector parallel to the z axis → the **k** vector

### (C) Unit Vectors in 3 Space

- So revisit the point A(2,3,5),
- We can write it in component form as:  $\vec{OP} = \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix}$
- Or we can write it in unit vector notation as

$$\vec{OP} = 2\vec{i} + 3\vec{j} + 5\vec{k}$$

### (D) 3D Vectors & Co-ordinate Geometry

- As we did in 2 space, we can work with specific points for the head and tail
- So if P(2,3,5) and Q(-1,6,-2), determine  $\vec{PQ}$  in component form and in unit vector form.
- Determine the length of  $\vec{PQ}$

### (D) 3D Vectors & Co-ordinate Geometry

- As we did in 2 space, we can work with specific points for the head and tail
- So if P(x<sub>1</sub>,y<sub>1</sub>,z<sub>1</sub>) and Q(x<sub>2</sub>,y<sub>2</sub>,z<sub>2</sub>), determine  $\vec{PQ}$  in component form and in unit vector form.
- Determine the length of  $\vec{PQ}$

### (D) 3D Vectors & Co-ordinate Geometry

- As we did in 2 space, we can work with specific points for the head and tail

Let  $\vec{v}$  be the vector with initial point P(x<sub>1</sub>, y<sub>1</sub>, z<sub>1</sub>) and terminal point Q(x<sub>2</sub>, y<sub>2</sub>, z<sub>2</sub>). See the figure below.

### (E) Algebra with 3D Vectors

- Working with 3D vectors algebraically is very similar to working with 2D vectors
- Let  $a = \begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix}$  and  $b = \begin{bmatrix} b_x \\ b_y \\ b_z \end{bmatrix}$
- (1) addition/subtraction      (2) scalar multiplication

$$a + b = \begin{bmatrix} a_x + b_x \\ a_y + b_y \\ a_z + b_z \end{bmatrix} \quad a - b = \begin{bmatrix} a_x - b_x \\ a_y - b_y \\ a_z - b_z \end{bmatrix} \quad ka = k \begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix} = \begin{bmatrix} ka_x \\ ka_y \\ ka_z \end{bmatrix}$$

## (E) Algebra with 3D Vectors

- To help make our algebra work with vectors easier, let's make certain generalizations (rules) that are true for vector algebra
- Commutative property  $\rightarrow \mathbf{a} + \mathbf{b} = \mathbf{b} + \mathbf{a}$
- Associative property  $\rightarrow (\mathbf{a} + \mathbf{b}) + \mathbf{c} = \mathbf{a} + (\mathbf{b} + \mathbf{c})$
- Additive identity property  $\rightarrow \mathbf{a} + \mathbf{0} = \mathbf{0} + \mathbf{a} = \mathbf{a}$
- Additive inverse property  $\rightarrow \mathbf{a} + (-\mathbf{a}) = (-\mathbf{a}) + \mathbf{a} = \mathbf{0}$

## (F) Examples

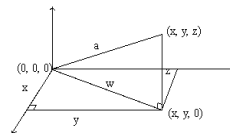
- Cirrito/HH text

## (F) Examples

- Given the point  $P(4,5,-7)$ , determine:
  - (a) its position vector
  - (b) a vector that is equal to  $OP$
  - (c) a vector that is anti-parallel to  $OP$
  - (d) how far the point  $P$  is from:
    - (i) the origin
    - (ii) the  $XZ$  plane
    - (iii) the  $x$ -axis

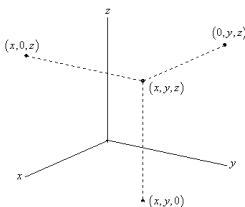
## (F) Examples

- The following diagram may help in Q(d)



## (F) Examples

- The following diagram may help in Q(d)



## (E) Examples

- Let's go back to parallelograms:
- Given  $A(-1,2,5)$  and  $B(2,0,3)$  and  $C(-3,1,0)$  and  $D(x,y,z)$
- Find the co-ordinates of  $D$  in parallelogram  $ABCD$  if:
  - (i)  $\overrightarrow{AB} = \overrightarrow{DC}$
  - (ii)  $\overrightarrow{AC} = \overrightarrow{BD}$

## Homework

- HW:
- Ex 16A #1c, 2c, 4a;
- Ex 16B.1 #2,3;
- Ex 16B.2 #2a, 3a, 5a
- Ex 16C #1h,2c, 5-8

